

Method and Apparatus for the Measurement of the Acoustic Impedance

FIELD OF THE INVENTION

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The present invention relates to a method and an apparatus for the determination of the acoustic impedance, and more particularly to the determination of the acoustic impedance of cavities such as the human ear.

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BACKGROUND OF THE INVENTION

A measurement system consisting of two components will conventionally be used for the determination of the acoustic impedance of a closed room. The two components are a microphone and a loudspeaker which are connected to an analysis unit. This arrangement is frequently supplemented by a third connector to apply static pressure.

A probe with three connectors is especially used for the measurement of the acoustic impedance of the ear in functional relationship to the static pressure for diagnostic purposes. The connectors thereby couple the probe, which is inserted into the ear channel, with a static pressure generator, a microphone and a loudspeaker.

The evaluation of the measurement will thereby be performed by electronic or computerized analysis units. The calibration of the measurement equipment takes place

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typically by use of a set of tubes with defined geometrical dimensions and acoustic behavior. The principle of Thévenin for the measurement of unknown impedances is used for the characterization of the measurement system. The measurement system then may be represented by a voltage source and a first impedance.

The voltage will then be measured over a second series connected unknown impedance. This measured voltage stands in a direct coherence with the unknown impedance, whereby all magnitudes or parameters are complex functions of the frequency. The system now has first to be calibrated, e.g. the parameters of the system have first to be calculated by the use of calibrated impedances, i.e. with at least two calibrating impedances. If the parameters of the voltage source and the first impedance are known, the second unknown impedance may be determined by measuring the voltage over this second impedance. This method is described in detail in US 5,792,072.

Such a method and apparatus are described as well in US 4,289,143. A probe will thereby be entered closely into the entrance of the ear channel, thereby emitting short acoustic pulses of a broad wave band penetrating into the ear channel, and the respective response signals will be detected by a loudspeaker integrated as well in the probe and converted into electrical signals. Those signals will subsequently be digitalized and transformed into a Fourier series which then will be analyzed by a processor. The analysis will be made vis-à-vis stored values, which values have been determined by the antecedent application of the

method with two calibrated measuring impedances, such as two cylindrically measuring tubes with different dimensions. The processor or the analysis electronic respectively will be used at the same time for the
5 controlling of the pulse generator and eventually for the controlling of a static pressure generator as well, which may be connected to the probe as well.

But both of the described methods suffer of some disadvantages. A phase relation between the voltage of the
10 voltage source (or the system respectively) and the measured voltage over the second impedance is necessary to determine the second impedance (complex impedance). As this voltage cannot directly be observed by the principle of Thévenin, the phase has to be determined by way of a
15 detour.

Furthermore, those methods are no longer usable if the stimulation changes between calibration and measurement, i.e. if the voltage of the generator is not constant. After all, noise effects occurring during the active measurement
20 of the voltage over the second impedance will falsify the result.

The universal application of the measurement method according to US 4,289,143 for the measuring of general acoustic impedances will as well lead to geometrical
25 problems. As all three connectors for loudspeaker, microphone and static pressure generator are arranged in the same plane at the exit of the probe, in which plane the impedance to be measured is defined, the coupling of individual acoustic elements will lead to geometrical

problems, especially if the opening cross section is smaller than the diameter of the probe.

This is for example the case by coupling small tubes, be it as reference impedances for the calibration of the
5 measurement equipment or as objects to be measured. It is essentially in such cases to use additional coupling volumes. The use of complex modules such as wind shields or membranes is as well problematic. Furthermore in the field of ear measurement, the risk of choking the probe occurs,
10 which rules out the measurement or destroys the calibration and therefore falsifies the result.

OBJECT OF THE INVENTION

15 An object of the present invention is to provide a measuring method for an easy and simple measurement of impedances by overruling the known disadvantages. A further object is to provide an apparatus for performing such measurements.

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SUMMARY OF THE INVENTION

In accordance with the present invention, the method for the determination of the acoustic impedance comprises the
25 steps of sending out acoustic signals with a probe arranged at the area to be measured comprising a mean for the acoustic stimulation and a microphone and transforming the

received signals into electrical signals. The electrical signals will then be transferred to an analysis unit in which the magnitude or value of the impedance will be determined. As a calculation base, the defined stimulation
5 will be followed by a chain transfer matrix in form of a twoport until the impedance to be measured, whereby the voltage ration between stimulation and impedance is described as a dimensionless transfer function in form of a complex function of the stimulation frequency. As series of
10 acoustic calibration signals will be generated by a number of known acoustic impedances covering different calibration scopes by means of the defined stimulation. The calibration signals received by the microphone are recorded in the probe and the electric values are merged together with the
15 respective voltage values of the stimulation for evaluating the results of the respective transfer functions. The transfer functions of the calibration signals will then be merged together into an over determined linear system of equations and by solving this system of equations the two
20 coefficients will be calculated. Finally the impedance to be measured will be determined by evaluating the transfer function under defined stimulation by use of the coefficients determined by the foregoing calibration.

The stimulation may be observed or measured due to the
25 description of the relation between stimulation and voltage over the impedance to be measured with a chain matrix model in contrary to the model of Thévenin. Thus the determination of the phase relation between those values will be much easier. Furthermore, the proposed use of a
30 dimensionless transfer function leads to a calculation of

the impedance independently especially from the stimulation voltage.

Therefore, the mathematical model of the transfer between stimulation and microphone in relation to the voltage

5 transfer will be described completely by the two coefficients a_{11} and a_{12} of the chain matrix, according the equation:

$$U_{ab} = \frac{u_a}{u_b} = a_{11} + a_{12}/Z$$

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Those coefficients will now be determined on the basis of known calibration impedances by solving the respective over determined linear system of equation. Thus a simpler execution and calculation of the calibration may be
15 performed with respect to the known method by Thévenin.

The individual transfer functions by the execution of the calibration will be calculated from the quotient between the auto power spectrum $U_a U_a^*$ and the average of the cross power spectrum $U_b U_a^*$. Thus any interferences of the
20 measuring magnitude u_b will favorably be suspended, i.e. the voltage of the impedance measured by use of the microphone. At least two calibration impedances will be used for this purpose.

In a preferred embodiment, the system of equation will be
25 solved in terms of minimum squares.

In a further embodiment, the stimulation will be made by use of a controlled frequency generator over a loud

speaker. A broadband signal will thereby be produced, e.g. a white noise. The spectrum of frequency may be reduced to a determined bandwidth according the employment.

In a further embodiment, the use of two serial connected
5 twoports, i.e. two successively arranged chain matrices, is proposed as computation model, to cover the universal measurement of geometrically different measuring objects, which may be coupled over an additional adaptor. The microphone will then be positioned between the output of
10 the first twoport and the input of the second twoport, i.e. - the respective measurement will be performed between the two matrices, whereas the impedance is arranged at the outlet of the second matrix. The first matrix thus represents the model of the base element of the measuring
15 probe and the second matrix the model of the adapter arranged after the microphone. The base element of the probe may be composed identically for any applications and thereby builds up constant circumstances. The adaptor is arranged detachable with the base element and implemented
20 in a great number of different embodiments, especially with different geometrical dimension, according the field of application. The individual adapters are therefore having different system behaviors and a separate calibration has to be performed for each adapter.

25 The model consisting of 8 matrix elements is preferably reduced to three base parameters in form of complex functions of the frequency, describing the model sufficiently precise.

The three parameters may be determined by solving the linear system of equation resulting by the measurement of three different calibration impedances and may subsequently be used for the calculation of the unknown impedance. Again
5 only the transfer functions between stimulation and voltage of the microphone will have to be measured.

In a further embodiment, an acoustic resistor will be arranged between the stimulation and the microphone. It has been shown that the accuracy of the measurement will thus
10 be further enhanced. The resistor may be optimized in view of the sensitivity due to microphone errors.

In a further embodiment, the method will be used to determine the acoustic ear impedance.

The use of two serial connected twoports considers the use
15 of different coupling means, such as foam plugs, ear moulds, hearing device shells etc.

The need of flexibility with respect to the coupling in the field of ear impedance measurement will be advantageously accomplished by the present invention, which allows the
20 measurement with individual adaptors which are quickly built and calibrated.

In a further embodiment, an apparatus for the determination of the acoustic impedance comprising a probe, a microphone and a speaker is proposed, whereby the microphone is
25 arranged between both twoports.

BRIEF DESCRIPTION OF THE DRAWINGS

Examples of the present invention will now be described in detail with reference to the accompanying drawing in which:

Fig. 1 is a schema of the determination of a impedance
5 according the Thévenin principle;

Fig. 2 is a schema of an embodiment of the inventive method of measuring impedances using a chain matrix;

Fig. 3 is an embodiment of the linear system of equations underlying the inventive method;

10 Fig. 4 is a further schema of a further preferred embodiment of the inventive method with two matrices;

Fig. 5 is the schematic arrangement of a measuring apparatus for performing the method according Figure 4.

15 DETAILED DESCRIPTION OF THE INVENTION

Figure 1 shows schematically the principle of a measurement of an unknown impedance according Thévenin. This principle is based on a base system, which is theoretically described
20 as a voltage source with the complex voltage u_a and a total serial impedance Z_a . This base system serves for the stimulation and transforming of the voltage to the impedance Z to be measured. A voltage u_b may be measured over this load impedance Z . The values stand thereby in the
25 following relation:

$$Z = \frac{u_b Z_a}{u_a - u_b}$$

The parameters u_a und Z_a may be calculated by performing measurements with at least two known calibration impedances $Z(1)$ and $Z(2)$. The load impedance Z can thus be determined by the measuring of the voltage u_b according the above
5 equation. It has to be considered that all magnitudes or values respectively are complex functions in relation to the frequency of the stimulation voltage u_a . That is the reason why the phase relation between u_a und u_b has to be known, which phase relation has to be observed separately
10 as u_a cannot directly be observed or measured with such a system.

Another model is now proposed by the present invention to overcome this disadvantage, which model is as an example shown by the schema according figure 2. The stimulation by
15 use of a generator with the voltage u_a is considered as to be observed or measured and the borders of the base system will be drawn only after the generation of this stimulation voltage. A twoport with assigned chain transfer matrix A , which is described by the parameters a_{11} to a_{22} , will be
20 used as a model for the transfer system. Thus a dimensionless transfer function U_{ab} may be defined as a voltage relation between the input generator voltage u_a and the output or measuring voltage u_b over the impedance Z .

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$$U_{ab} = \frac{u_a}{u_b} = a_{11} + a_{12}/Z$$

Therefore, the base system is fully described with respect to the transfer of the voltage by the two parameters a_{11}

and a_{12} , whereas all values are complex functions in relation to the stimulating frequency.

The parameters a_{11} and a_{12} have now to be determined analog to the principle of Thévenin by measuring calibration
5 impedances Z_1, Z_2, \dots, Z_n , which will be applied into an over determined linear system of equation according figure 3.

To suppress interferences of the measuring value u_b , the respective transfer functions of the linear system of equation will preferably be calculated by use of averaging
10 techniques. Each transfer function U_a will thereby be calculated by the division of the measured auto power spectrum $U_a U_a^*$ through the average cross power spectrum $U_b U_a^*$ according the formula :

15
$$U_{ab} = \frac{U_a U_a^*}{U_b U_a^*}$$

The solution of the linear system of equation according figure 3 in terms of minimum squares provides the two parameters a_{11} and a_{12} . The transfer function U_{ab} may be
20 measured from the measuring of the voltage relation u_a/u_b for a unknown impedance Z and thereafter the impedance Z may be evaluated by the following formula :

$$Z = \frac{a_{12}}{U_{ab} - a_{11}}$$

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As a great advantage, no effort has to be taken to determine the phase between u_a and u_b , and the measuring method is independent from the stimulation voltage due to the use of a dimensionless transfer function U_{ab} . A reduced
5 sensitivity of the measuring system compared to measuring noise will be achieved by using averaging techniques, e.g. the sensitivity compared to microphone noise and interference noise are strongly reduced.

A measuring device for the precise determination of
10 impedances of cavities may now be simply built by using the present principle, and may be operated with common measuring and computing means. The calibration of such measuring devices may be simply performed by using the linear system of equation, which will make its use economic
15 even outside of laboratory conditions.

The inventive method is suitable for use of measuring the acoustic impedance of the human ear, whereby the measuring can take place under different static pressure situations analog to the known methods.

20 The principle has been further developed for the universal practical use, especially to use the base apparatus for different measurement kinds with different geometries.

The use of different adapters to be connected with the base apparatus is proposed to cover the different measuring
25 environments. Those adaptors naturally modify the base system and disallow the use of the principles of Thévenin, as the voltage over the microphone does no longer represents the actual sound pressure over the impedance to be measured.

The inventive principle will be extended with an adaptor matrix B, as shown schematically in figure 4. The voltage U_b will not be gripped at the end over the impedance to be measured but between the two matrices A and B. The

5 advantage is that in the practical realization of such a measuring apparatus the microphone has not to be arranged headmost at the location of the impedance to be measured but some way backwards, thus on the one hand protecting the microphone and on the other hand leaves open the freedom of
10 design of any adaptor, as shown schematically in figure 5. Figure 5 shows schematically a probe for the execution of the method described above comprising a loudspeaker 1 and a microphone 2 arranged within a connecting channel 4. An acoustic resistor 5 is arranged in the connecting channel 4
15 between the loudspeaker 1 and the microphone 2. The connecting channel 4 leads into an adapter 3, which may be arranged unblockable or detachable respectively with the housing of the probe. Alternatively the resistor 5 may be arranged after the microphone 2 at the end of the
20 connecting channel 4 or the adapter 3.

The 8 parameters a_{11}, \dots, a_{22} and b_{11}, \dots, b_{22} of both matrices A and B may be reduced for such an application to three parameters d_1 , d_2 and d_3 to describe the impedance Z, according the following equation:

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$$Z = \frac{d_2}{U_{ab} - d_1} - d_3$$

Those three parameters d_1 , d_2 and d_3 are analog to the antecedent specified parameters a_{11} and a_{12} as well complex functions with respect to the stimulation frequency.

According to the antecedent specified approach for the calculation of the parameters a_{11} and a_{12} , an over
5 determined linear system of equation can be formulated, which may provide three parameters d_1 , d_2 and d_3 by use of at least three known calibrating impedances and solving the system of equation in terms of minimum squares.

- 10 An optimal accuracy of the measurement will be achieved by specifically frequency or impedance weighing of the equation. Optimal measuring accuracy can thus be achieved for a defined application area.

The arranging of an acoustic resistor between the
15 stimulation and the microphone has been shown as an advantage. The accuracy of the measuring device may further be increased by use of such an acoustic resistor. The resistor may be optimized in view of its sensitivity concerning faults of the microphone for a determined range
20 of impedance.

Besides the application in the field of hearing devices, the present method may be used universally for general purposes of the measuring of impedances, especially in the field of quality control of porous bodies, membranes or
25 textiles. Especially the possibility of the use of individual adaptors with different geometrical dimensions allows the universal use of such a measuring apparatus according the present claimed method.